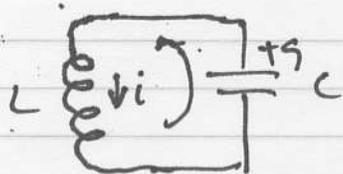


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HW 3

①

①



$$\text{VOLTAGE ACROSS CAPACITOR} = \frac{q}{C}$$

$$\text{VOLTAGE ACROSS INDUCTOR} = L \frac{di}{dt}$$

$i \propto \frac{dq}{dt}$ but since q is
ASSUMED to be decreasing
 for positive i

KIRCHHOFF'S LAW: $\Rightarrow i = -\frac{dq}{dt} \quad \frac{di}{dt} = -\frac{d^2q}{dt^2} = -\ddot{q}$
 equating VOLTAGE DROPS with VOLTAGE GAINS around loop

$$L \frac{di}{dt} = \frac{q}{C} \Rightarrow L \ddot{q} + \frac{q}{C} = 0 \Rightarrow \boxed{\ddot{q} + \omega_0^2 q = 0}$$

ASSUME SOLUTION OF FORM $q = A \cos(\omega_0 t + \phi)$ with two adj. constants

$$\text{where } \omega_0 = \frac{1}{\sqrt{LC}}$$

$$\text{checks: } \ddot{q} = -\omega_0^2 A \cos(\omega_0 t + \phi)$$

$$\text{INITIAL CONDITIONS } \left. \begin{array}{l} \text{AT } t=0 \\ \} \end{array} \right. = q_0 = CV_1 = A \cos \phi \rightarrow A = \frac{CV_1}{\cos \phi}$$

$$i = \dot{q} = 0$$

$$\dot{q} = -\omega_0 A \sin(\omega_0 t + \phi)$$

$$0 = -\omega_0 A \sin \phi \rightarrow \phi = 0 \quad \text{AND } \cos \phi = 1$$

$$\therefore A = CV_1$$

$$\text{COMPLETE SOLUTION } q(t) = CV_1 \cos \frac{t}{\sqrt{LC}}$$

②

① $m = 1.0 \text{ kg}$ $S = 64 \text{ N/m}$ b (frictional coeff) unknown

GIVEN $\ddot{y} + \frac{b}{m}\dot{y} + \frac{S}{m}y = 0$, ASSUME $y = e^{pt}$

we found $p = \frac{-b}{2m} \pm \sqrt{\left(\frac{b}{2m}\right)^2 - \omega_0^2}$ where $\omega_0 = \sqrt{\frac{S}{m}}$

UNDAMPED
natural frequency = $\sqrt{\frac{64 \text{ N/m}}{1 \text{ kg}}} = 8 \text{ sec}^{-1}$ $f = \frac{\omega_0}{2\pi} = 1.3 \text{ Hz}$

This suggests that the circuit would oscillate many times in 10 s if the damping is light,

⇒ take solution to be of form π "light damping"
(NOT ENOUGH INFO TO SOLVE FOR TWO CONSTANTS)

$$y(t) = A e^{-\frac{bt}{2m}} \cos(\omega_f t + \phi) \quad \omega_f = \sqrt{\omega_0^2 - \left(\frac{b}{2m}\right)^2}$$

(a) PROBLEM STATES THAT AMPLITUDE DECREASES FROM A to A/e
IN 10 SEC

$$\therefore \frac{b}{2m} = \frac{1}{10} \text{ s}^{-1} \text{ so } b = \frac{2m}{t} = \frac{2 \cdot 1.0 \text{ kg}}{10 \text{ s}} = 0.2 \text{ kg/s}$$

(b) $\gamma = \frac{b}{m} = 0.2 \text{ s}^{-1}$

$$Q = \frac{\omega_0}{\gamma} = \frac{8}{0.2} = 40$$

(c) CRITICAL DAMPING IS DEFINED AS $\omega_f = 0 = \sqrt{\omega_0^2 - \left(\frac{b}{2m}\right)^2}$

$$\omega_0^2 = \left(\frac{b}{2m}\right)^2$$

$$\text{or } \gamma^2 = 4\omega_0^2$$

$$\text{so } Q = 1/2$$

$$b = 2m\omega_0 = 16 \text{ kg s}^{-1}$$

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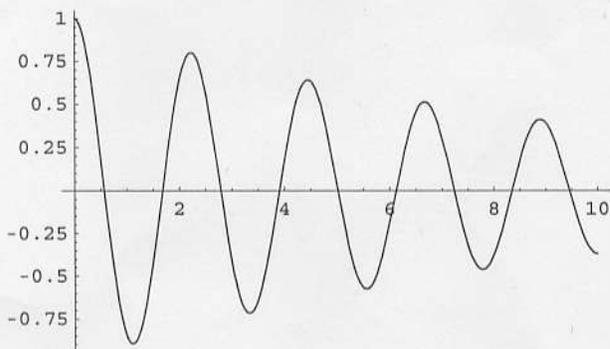
(2)

■ Damped SHM equation CHECK OF RESULT PROBLEM 11.2 part (a)

```
result1 = NDSolve[{y''[t] + 0.2 y'[t] + 8 y[t] == 0, y[0] == 1, y'[0] == 0}, y, {t, 0, 10}]
```

```
{y -> InterpolatingFunction[{{0., 10.}}, <>]}
```

```
plot1 = Plot[y[x] /. result1, {x, 0, 10}];
```



$$3. \quad \psi = A e^{-\delta t/2} \cos(\omega_f t + \phi)$$

AMPLITUDE IS GIVEN BY $A e^{-\delta t/2}$

AT TIME t THIS DECREASES BY $\frac{1}{2}$

$$\frac{1}{2} = e^{-\delta t/2} \Rightarrow \ln(0.5) = -\delta t/2$$

$$t = -\frac{2 \ln(0.5)}{\delta} = \frac{1.39}{\delta}$$

4.

$\psi(t)$ AS ABOVE

THE COS TERM GIVES SUCCESSIVE MAXIMA FOR $T = \frac{2\pi}{\omega_f}$

THIS IS WHAT THE PROBLEM ASKS US TO SHOW SO

WHY DOESN'T $e^{-\delta t/2}$ TERM AFFECT THE TIME BETWEEN MAXIMA? (IT DOES AFFECT THE POSITION OF THE MAXIMA, SEE FRENCH)

AT MAX OF $\psi(t)$, $\dot{\psi}(t) = 0 = -\frac{\gamma}{2} t A e^{-\gamma t/2} \cos(\omega_f t + \phi) - \omega_f A e^{-\gamma t/2} \sin(\omega_f t + \phi)$

THIS LEADS TO $\frac{\sin(\omega_f t + \phi)}{\cos(\omega_f t + \phi)} = \tan(\omega_f t + \phi) = -\frac{\delta}{2\omega_f}$

THIS IS PERIODIC IN t WITH PERIOD $T = \frac{2\pi}{\omega_f}$ (for maxima)

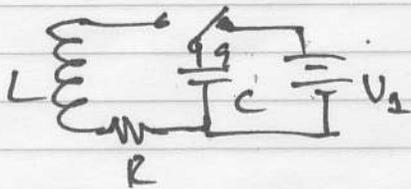
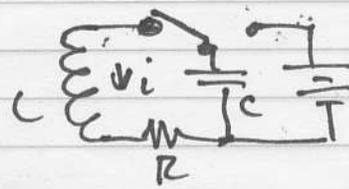
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(4)

⑤

RLC CIRCUIT


 \rightarrow
(t=0)


$$L \frac{di}{dt} + Ri + \frac{q}{C} = 0$$

$$q_0 = CV_1$$

$$i = \dot{q} \quad \frac{di}{dt} = \ddot{q} \quad \Rightarrow \quad \ddot{q} + \frac{R}{L} \dot{q} + \frac{1}{LC} q = 0$$

$$\begin{cases} \omega_0 = \frac{1}{\sqrt{LC}} \\ \omega_f = \sqrt{\omega_0^2 - (\frac{R}{2L})^2} \end{cases}$$

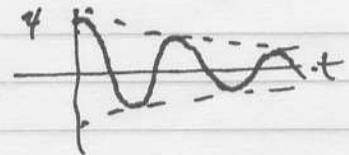
Assuming $q = A \cos(\omega_f t + \phi) \cdot e^{-\gamma t/2}$

$$q(0) = CV_1 = A \cos \phi \quad \Rightarrow \quad A = \frac{q(0)}{\cos \phi} = \frac{CV_1}{\cos \phi}$$

$$\dot{q}(t) = -\frac{\gamma}{2} A e^{-\gamma t/2} \cos(\omega_f t + \phi) - \omega_f A e^{-\gamma t/2} \sin(\omega_f t + \phi)$$

$$\dot{q}(0) = 0 = -\frac{\gamma}{2} A \cos \phi - \omega_f A \sin \phi$$

$$\Rightarrow \tan \phi = -\frac{\gamma}{2\omega_f}$$



$i=0$
WHEN
SWITCH
CLOSED
AT $t=0$

(a) So $q(t) = \frac{CV_1}{\cos \phi} e^{-\gamma t/2} \cos(\omega_f t + \phi)$ where $\phi = \tan^{-1}\left(\frac{-\gamma}{2\omega_f}\right)$

* SURPRISINGLY A IS NOT EQUAL TO $q(0)$. THIS IS

BECAUSE THE RESISTOR INTRODUCES A TIME LAG INTO THE SOLUTION. CHECK: $q(0) = \frac{CV_1}{\cos \phi} \cdot \cos \phi = CV_1$

(b) CRITICAL DAMPING FOR $\gamma^2 = 4\omega_0^2$ OR $\left(\frac{R}{L}\right)^2 = 4\left(\frac{1}{LC}\right)$

OSCILLATES FOR

$$R < 2\sqrt{L/C}$$